

GLOBALSAT GPS Engine Board

Hardware Datasheet

Product No : MR-332(SMA)

Version 1.0



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|------------|------|-------|---------|
| Issue Date | APPR | CHECK | PREPARE |
| 2013/07/03 | Ray | | Mason |

Product Description

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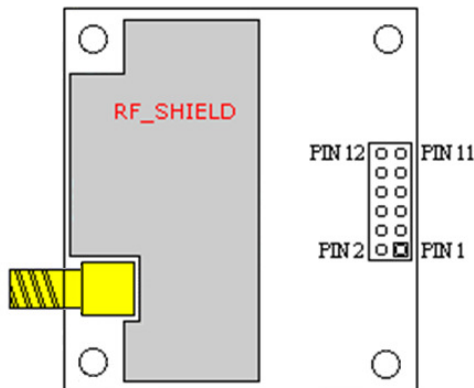
MR-332 is a compact, high performance, and low power consumption GPS engine board. The chipset is powered by MediaTek, it can provide you with superior sensitivity and performance even in urban canyon and dense foliage environment. MR-332 is suitable for the following applications:

- Automotive navigation
- Personal positioning
- Fleet management
- Marine navigation

Product Features

- MediaTek high sensitivity solution
- Support 22 tracking / 66 acquisition-channel GPS receiver
- Very high sensitivity (Tracking Sensitivity: -165dBm)
- Extremely fast TTFF (Time To First Fix) at low signal level
- Support RS-232 interface, baud rate base on firmware setting.
- Support Serial port NMEA output.
- Built-in LNA
- Compact size (40.6mm x 35.0mm x 13.7mm) suitable for space-sensitive application
- Support NMEA 0183 V3.01 (GGA, GSA, GSV, RMC)
- Supports GPS, SBAS ranging (WASS/EGNOS/MSAS/GAGAN), QZSS.

Product Pin Description



| PIN Number(s) | Name | Type | Description | Note |
|---------------|-----------|------|--|------|
| 1,8,9,12 | GND | P | Ground | |
| 2 | VBAT | P | This is the power input for the SRAM, RTC and charging back up battery. To achieve the faster start-up offered by a hot or warm start, a backup power must be connected. When VBAT released, the full battery can keep the SRAM and RTC few hours. The VBAT voltage should be between 3.3V and 3.6V. When VCC is connected to the Power, VBAT can be floating. | |
| 3 | VCC | P | This is the main power supply to the engine board. (3.8Vdc to 5.5Vdc) | |
| 4 | RESET | I | Push Button Reset Input (Active Low) | |
| 5,10 | RESERVED | | MR-332 reserved pin, just NC. | |
| 6 | TXD | O | This is the main transmits channel for outputting navigation and measurement data to user's navigation software or user written software. Baud rate based on firmware setting. | |
| 7 | RXD | I | This is the main receive channel for receiving software commands to the engine board from MTK software or from user written software. Baud rate based on firmware setting. | |
| 11 | TIMEPULSE | O | This pin provides one pulse-per-second output from the board, which is synchronized to GPS time. If do not use it, Just NC. | |

Electrical Specification

Absolute Maximums Ratings

| Parameter | Min. | Typ. | Max. | Conditions | Unit |
|-------------------------------|------|-------|------|------------|----------|
| Power | | | | | |
| Power supply voltage(VCC) | 3.8 | 5.0 | 5.5 | | V |
| Backup battery supply | 3.3 | | 3.6 | | V |
| Main power supply Current | | 25 | | 5V | mA |
| Backup battery supply Current | 4.5 | 5 | 5.5 | 3.3V | uA |
| SMA Connector | | | | | |
| Input Impedance | | 50 | | | Ω |
| Operating Frequency | | 1.575 | | | GHz |
| RF Output Power | | 3.3 | | | V |

DC Electrical characteristics

| Parameter | Symbol | Min. | Typ. | Max. | Conditions | Units |
|-------------------------------|----------|------|------|------|------------|-------|
| I/O Low Level Output Voltage | V_{OL} | | | 0.42 | | V |
| I/O High Level Output Voltage | V_{OH} | 2.38 | | | | V |
| I/O Low Level Input Voltage | V_{IL} | -0.3 | | 0.7 | | V |
| I/O High Level Input Voltage | V_{IH} | 2.1 | | 3.6 | | V |

RS-232 Receiver/Transmitter characteristics

| Parameter | Min. | Typ. | Max. | Conditions | Units |
|------------------------------|-----------|-----------|------|------------|-------|
| EIA-232 Input Voltage Range | -30 | | +30 | | V |
| EIA-232 Input Threshold Low | 0.6 | 1.2 | | | V |
| EIA-232 Input Threshold High | | 1.6 | 2.4 | | V |
| Output Voltage Swing | ± 5.0 | ± 5.2 | | | V |

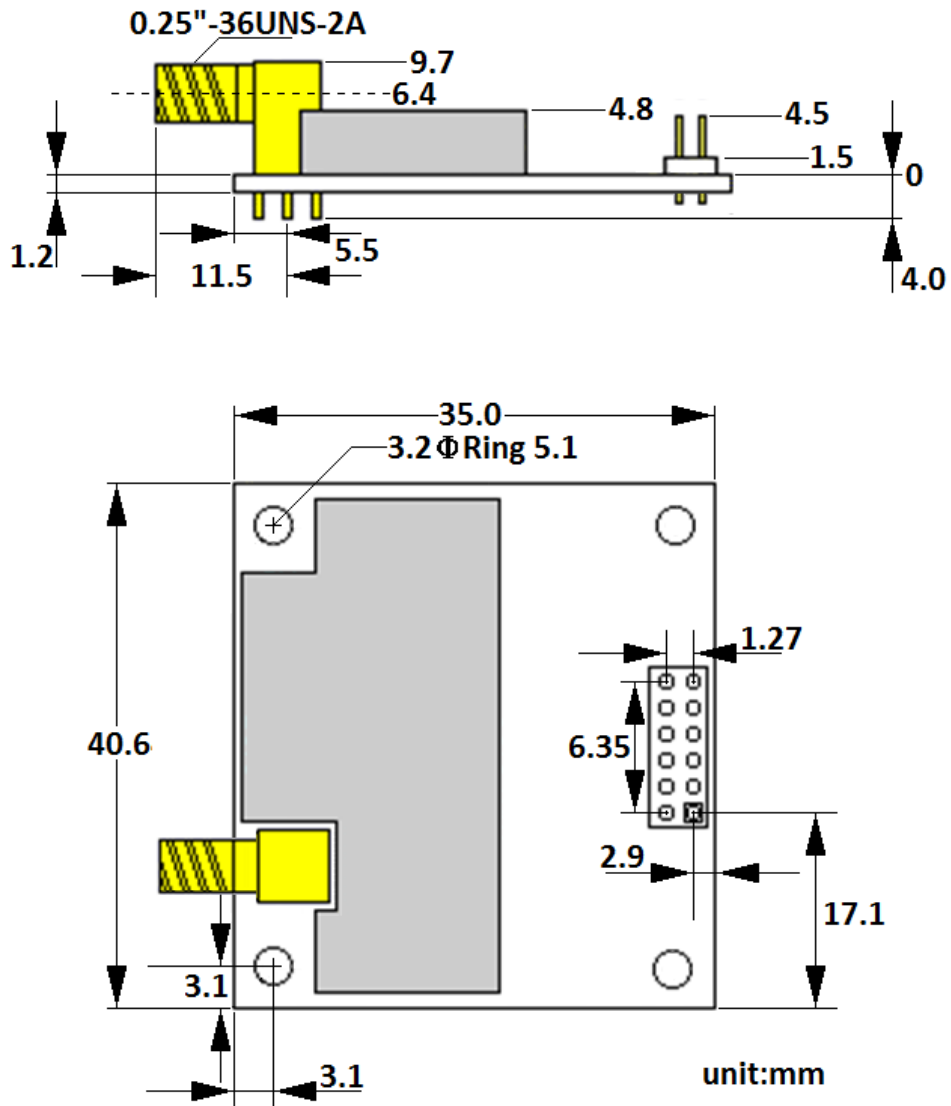
Environmental Characteristics

| Parameter | Min | Typ | Max | Unit |
|-----------------------|-----|-----|-----|--------------------|
| Humidity Range | 5 | | 95 | % non-condensing |
| Operation Temperature | -40 | 25 | 85 | $^{\circ}\text{C}$ |
| Storage Temperature | -40 | | 85 | $^{\circ}\text{C}$ |

Receiver Performance

| | | |
|------------------------------|--|------------------------------|
| Sensitivity (Chipset) | Tracking : Acquisition (cold / hot) : | -165dBm -148dBm / -163dBm |
| Time-To-First-Fix | Cold Start – Autonomous Warm Start – Autonomous Hot Start – Autonomous | < 35s < 35s < 1s |
| Horizontal Position Accuracy | Autonomous SBAS | < 3m (2D RMS) <2.0m |
| Velocity Accuracy | Speed Heading | < 0.01 m/s < 0.01 degrees |
| Reacquisition | 0.1 second, average | |
| NMEA Update Rate | Output data format based on firmware setting | |
| Maximum Altitude | < 18,000 meter | |
| Maximum Velocity | < 515 meter/ second | |
| Maximum Acceleration | < 4G | |

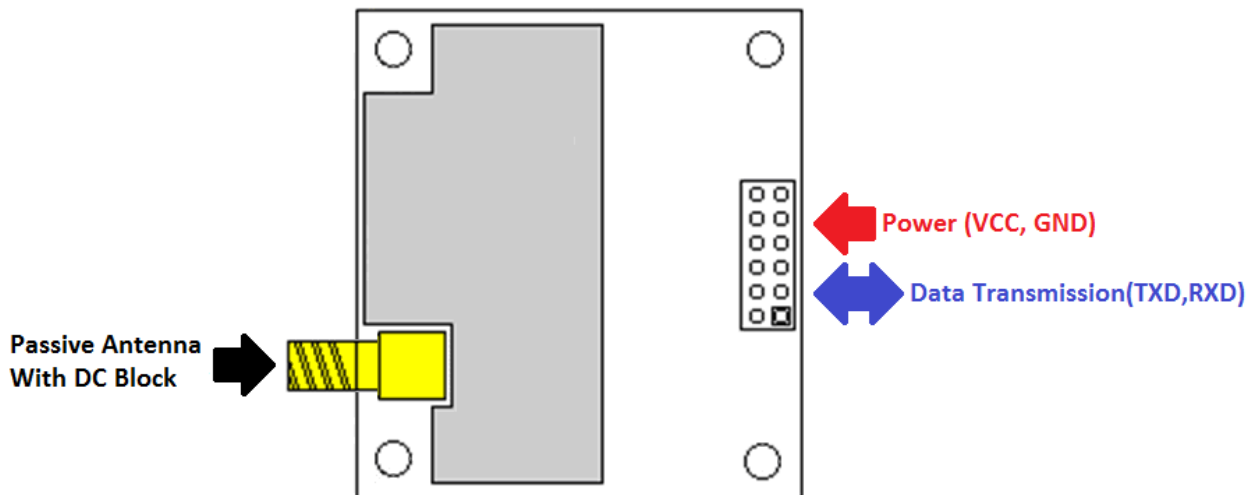
Package Dimensions



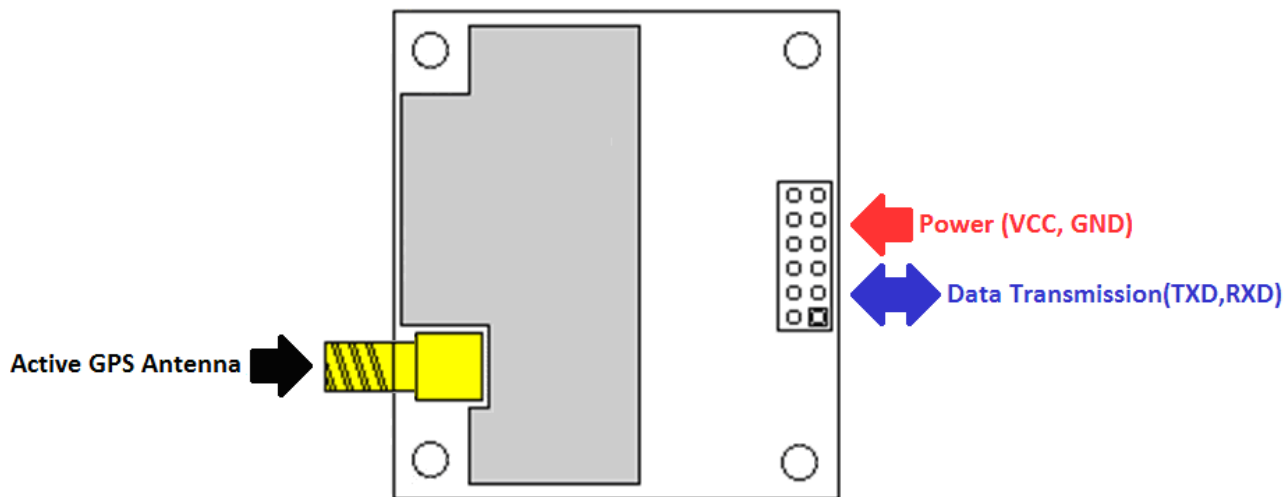
| | |
|------------|------------------------------------|
| Type | 12-pin header male |
| Dimensions | 40.6 mm * 35.0 mm * 13.7 mm ±0.2mm |

Application

Application circuit with passive antenna



Application circuit with active antenna



Recommended Active Antenna

GPS Active Antenna Specifications (Recommendation)

| | | | |
|-------------------|----------------|------------------------|-----------------|
| Frequency: | 1575.42 + 2MHz | Amplifier Gain: | 18~22dB Typical |
| Axial Ratio: | 3 dB Typical | Output VSWR: | 2.0 Max. |
| Output Impedance: | 50Ω | Noise Figure: | 2.0 dB Max |
| Polarization: | RHCP | Antenna Input Voltage: | 2.85V (Typ.) |

Reversion history

| Reversion | Date | Name | Status / Comments |
|-----------|----------|-------|-------------------|
| V1.0 | 2013/7/3 | Mason | Initial Version |
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